

# AUTOMATIC LANDSLIDE MAPPING USING PEAK GROUND VELOCITY AND SENTINEL-1 IMAGERY

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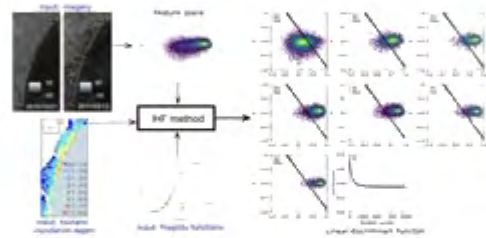
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## BACKGROUND

第20回 環境リモートセンシングシンポジウム

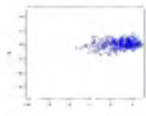
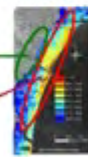
Previously, we proposed a method for damage mapping by the fusion of remote sensing, disaster demand intensity, and fragility functions



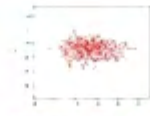
## CURRENT PROBLEM: THERE ARE NOT FRAGILITY FUNCTIONS

We can extract building samples from this area and assume with high certainty that those are non-collapsed buildings

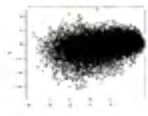
In this area we have both non-collapsed and collapsed buildings. We need to identify collapsed buildings



known database composed of only one class (498 buildings).



Unlabeled dataset but we know it is composed of 2 classes.

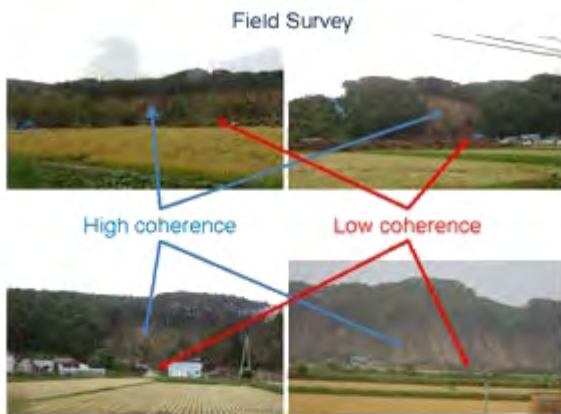
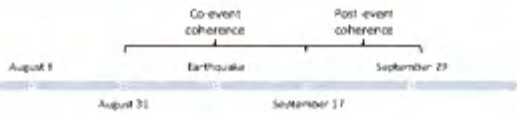


Complete sample space. About 30,000 samples. We need to classify.

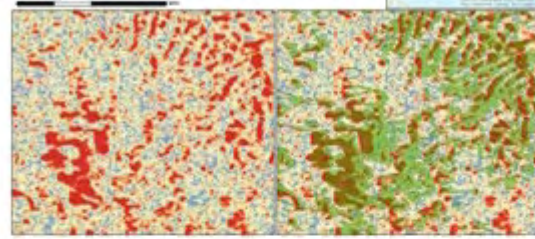
## STUDY AREA AND DATA SET



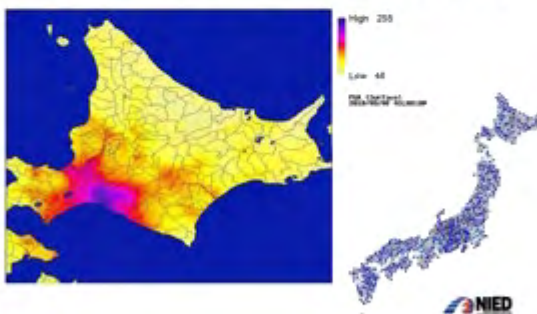
Pass direction: Descending  
 Polarization: VV VH  
 Product level: L1  
 Product type: SLC  
 Relative orbit: 46



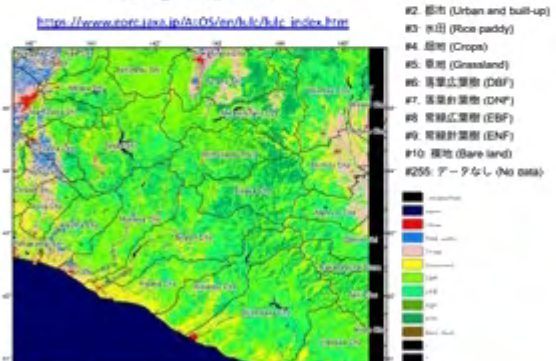
## LANDSLIDE EXHIBIT LARGE POST-EVENT COHERENCE



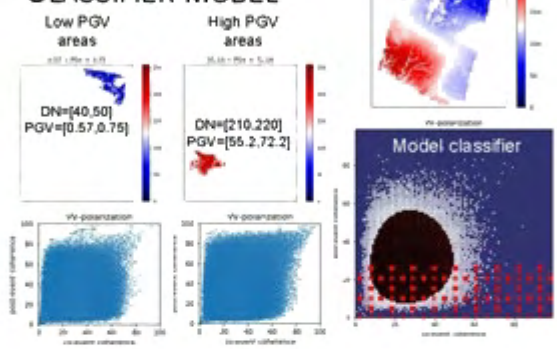
## DEMAND: PEAK GROUND VELOCITY (PGV)



## LAND USE MAP



### FEATURE SPACE AND CLASSIFIER MODEL



### EXAMPLE: STUDY AREA



### EXAMPLE: PREDICTIONS



### EXAMPLE: STUDY AREA



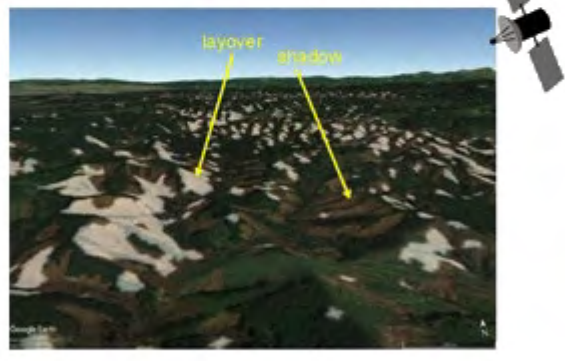
### EXAMPLE: PREDICTIONS



### LAYOVER AND SHADOWING EFFECTS



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### LAYOVER AND SHADOWING EFFECTS



### CONCLUSIONS

- The post-event coherence identifies bare land induced by landslide.
- The post-event coherence cannot be used to identify the landslide extent.
- The peak ground velocity can be used to train a classifier model in near real time.
- Landslides located in the layover areas can be identified.
- Landslides located in radar-shadow areas cannot be identified.
- Both, ascending and descending SAR images are necessary to perform a complete landslide mapping (**Future work**).

### THANK YOU

